

# Wideband Feedback Systems

## Full-Function Instability Control System

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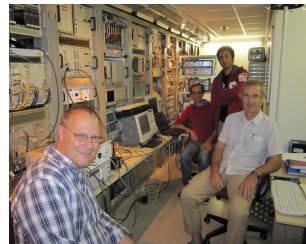
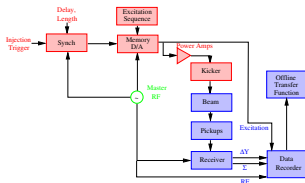
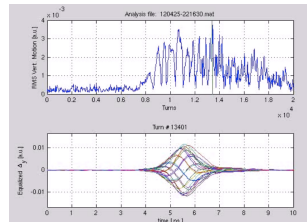
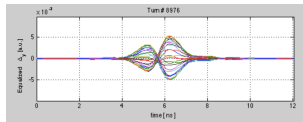
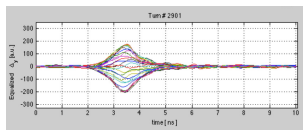
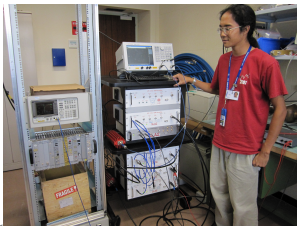
<sup>4</sup>LNF-INFN

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# Review Charge and Why are we here?

- Charge to the Review Committee for the Proposed LARP Project Scope and Plans
  - 1. Can the proposed project scope fit within the schedule and budget guidance given?
  - 2. Are the proposed cost, cost profiles and schedules reasonable?
  - 3. Is the plan to mitigate external schedule changes within the constraint of a fixed budget adequate?
  - 4. Is the technical plan proposed by each sub - project optimally developed? Are there additional technical risks that should be considered?
  - 5. Is the proposed management structure appropriate for the scope and scale of the project?
  - 6. Are there additional comments the Committee feels are relevant, regarding either individual tasks or the project as a whole?
- To Paraphrase the Talking Heads, "How Did We Get Here?"

# Beam Measurements, Simulation models, Technology development, Driven Beams and Demo System



## SPS Ecloud/TMCI Instability R&D Effort

- Stabilize Ecloud and TMCI effects via GHz bandwidth feedback
- Proton Machines, Ecloud driven instability - impacts SPS as high-current LHC injector ( applicable also to LHC,PS)
  - Photoelectrons from synchrotron radiation - attracted to positive beam
  - Single bunch effect - head-tail ( two stream) instability
- TMCI - Instability from degenerate transverse mode coupling - may impact high current SPS role as LHC injector
- Multi-lab effort - coordination on
  - Non-linear Simulation codes (LBL - CERN - SLAC)
  - Dynamics models/feedback models (SLAC - LBL-CERN)
  - Machine measurements- SPS MD (CERN - SLAC )
  - Kicker models and simulations ( LNF-INFN,LBL, SLAC)
  - Hardware technology development (SLAC,KEK)
- Complementary to coatings, grooves, etc. for Ecloud control
- Also addresses TMCI, allows operational flexibility
- LARP feedback program provides novel beam diagnostics in conjunction with technology development



# Wideband Intra-Bunch Feedback - Considerations

The Feedback System has to stabilize the bunch due to E-cloud or TMCI, for all operating conditions of the machine.

- unstable system- minimum gain required for stability
- E-cloud - Beam Dynamics changes with operating conditions of the machine, cycle (charge dependent tune shifts) - feedback filter bandwidth required for stability
- Acceleration - Energy Ramp has dynamics changes, synchronization issues (variation in  $\beta$ ), injection/extraction transients
- Beam dynamics is nonlinear and time-varying (tunes, resonant frequencies, growth rates, modal patterns change dynamically in operation)
- Beam Signals - vertical information must be separated from longitudinal/horizontal signals, spurious beam signals and propagating modes in vacuum chamber
- Design must minimize noise injected by the feedback channel to the beam
- Receiver sensitivity vs. bandwidth? Horizontal/Vertical isolation?
- What sorts of Pickups and Kickers are appropriate? Scale of required amplifier power?
- Saturation effects? Impact of injection transients?
- Trade-offs in partitioning - overall design must optimize individual functions

## Extensions from existing 500 MS/sec. architectures

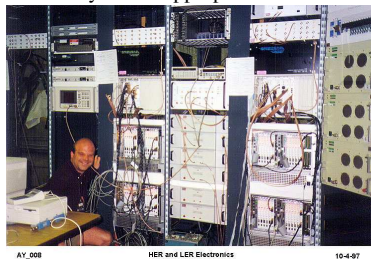
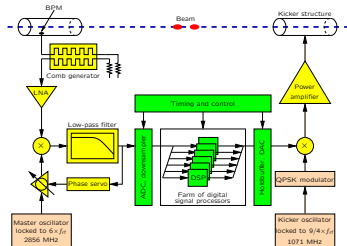
example/existing bunch-by-bunch feedback (PEP-II, KEKB, ALS, etc.)

- Diagonal controller formalism
- Maximum loop gain from loop stability and group delay limits
- Maximum achievable instability damping from receiver noise floor limits

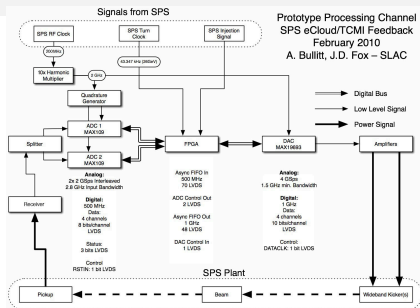
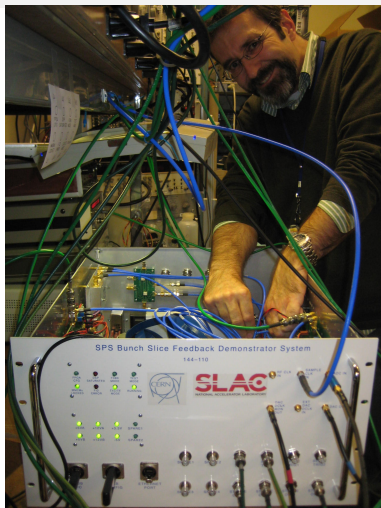
Electron-cloud effects act within a bunch (effectively a single-bunch instability) and also along a bunch train (coupling near neighbor bunches)

SPS and LHC needs may drive new processing schemes and architectures

Existing Bunch-by-bunch (e/g diagonal controller) approaches may not be appropriate



# 4 Gs/sec. 1 bunch SPS Demonstrator channel



- Proof-of-principle channel for 1 bunch closed loop tests in SPS - **commissioned November 2012**
- Wideband control in SPS after LS1 ( installation of wideband kicker)
- Reconfigurable processing - evaluate processing algorithms
- Technical formalism similar to 500 MS/sec feedback at PEP-II, KEKB, DAFNE

# Demonstration 1 bunch processor

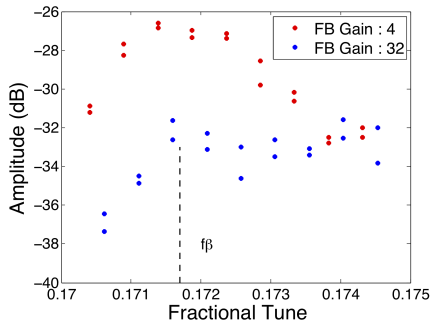
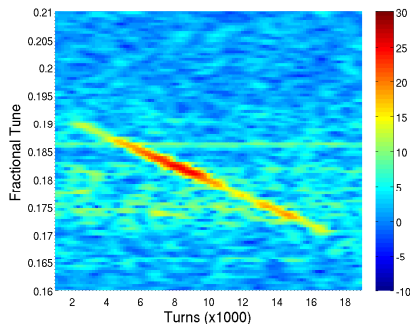
- Synchronized DSP processing system, initial 1 bunch controller
- Implements 16 independent control filters for each of 16 bunch “slices”
- Sampling rate 4 GS/sec. (3.2 in SPS tests)
- Each control filter is 16 tap FIR (general purpose)
- A/D and D/A channels
- Two sets of FIR filter coefficients, switchable on the fly
- Control and measurement software to synchronize to injection, manipulate the control filters at selected turns
- Diagnostic memories to study bunch motion, excite beams with arbitrary signals
- Reconfigurable FPGA technology, expand the system for control of multiple bunches
- What's missing? A true wideband kicker. Technology in development. These studies use a 200MHz stripline pickup as a kicker

## Recent MD Results Winter 2013

- MD trials (November, January, February) implement one-bunch feedback control
- 5 and 7 Tap FIR filters, gain variations of 30dB,  $\Phi$  varied positive/negative
- Studies of loop stability, maximum and minimum gain
- Driven studies ( Chirped excitations)
  - variation in feedback gain, filter parameters
  - multiple studies allow estimation of loop gain vs frequency (look at excitation level of several modes)
  - interesting to look at internal beam modes
- Feedback studies of naturally unstable beams

**We are just starting to analyze data, a few examples to stimulate discussion**

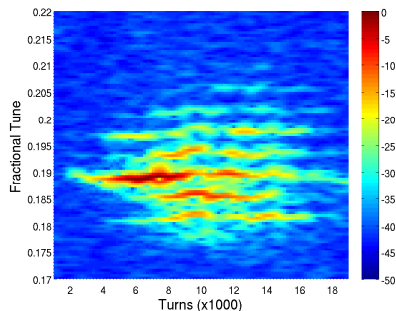
# Driven Motion Studies- closed loop feedback



- Driven chirp Pickup spectrogram (left )
- Chirp tune 0.19 - 0.17 turns 2K - 17K
- Tune 0.183 ( upper synchrotron sideband), Tune 0.175 Barycentric Mode
- Variation in Mode Zero Amplitude vs. loop gain ( right)
- Study changes in dynamics with feedback as change in driven response

# Positive Feedback Excitation of Internal Modes

- We need to characterize the response of the combined beam-feedback system
- Drive the beam using excitation chirps
- Vary the feedback gain and phase.
- Beam response shows effect of feedback on beam dynamics



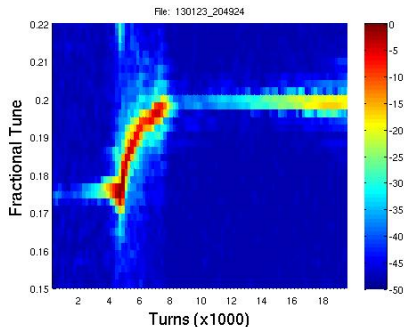
- An example spectrogram of unstable excited beam from the Feb 2013 MD
- ADC Input signal, positive feedback excitation turns 4000 to 12000 gain increased x4.
- turns 0 - 4k Negative FB, Positive turns 4K-12K, negative turns 12K - 20K

## Example feedback control of unstable beam

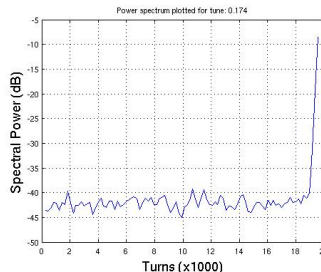
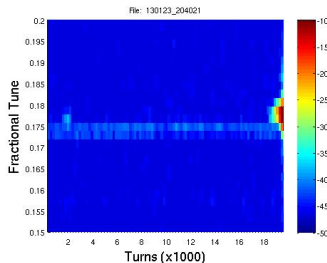
- SPS Cycle with chromaticity sweep to low (zero?) chromaticity after 1 sec into the cycle
- charge  $1 \times 10^{11}$  with slightly negative chromaticity
- With no FB the bunch is mode zero unstable (loses charge, seen in SUM signal and tune shift)
- Feedback was applied to beam after 2k (46 ms) turns, for a duration of 16 k turns
- Similar FIR filter design,  $\phi = 90^\circ$ ,  $G = 32$ .
- Stabilization of the dipole mode is clearly shown during the 16k turns when FB is ON
- The beam motion grows when the FB is switched off as shown at the end of the data recording, turns 18k – 20k.



# Feedback control of beam



- Spectrograms of bunch motion, nominal tune 0.175
- after chromaticity ramp at turn 4k, bunch begins to lose charge and gets tune shift.
- Feedback OFF -Bunch is unstable in mode zero (barycentric).

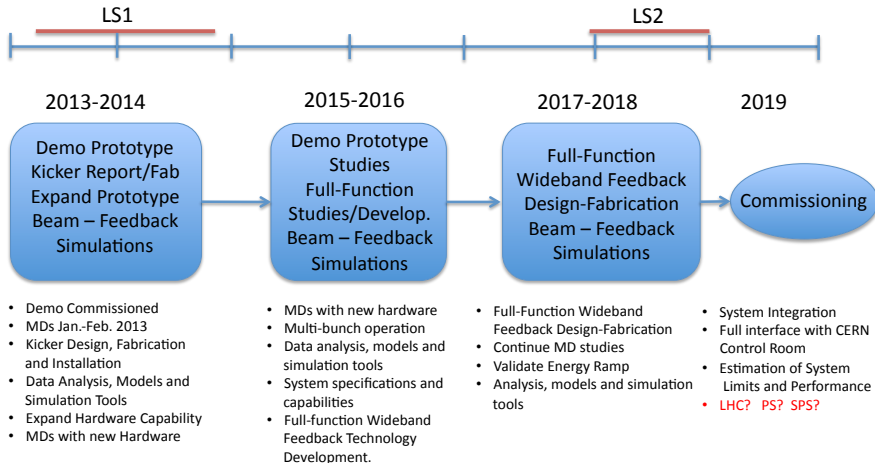


Feedback is switched off at turn 18K, beam then is unstable

## Near Term Research and Technology Plans

- Existing 1 bunch Demo System
  - FY13 - FY14 Expand processing capabilities, add synchronization, other features (SLAC)
  - FY13 - FY14 Fabrication of wideband Transverse Kicker proof of principle prototype (CERN and LNF)
  - FY15 - FY16 Tests of 1 bunch demo with wideband kicker
- How is the "full-function" Deliverable different from the "Demo System"? From a "production system"?
  - Demo System -initial capabilities to explore single bunch dynamics, explore control algorithms,limited bandwidth kicker
  - Demo System - to be used with proof of principle wideband kicker, validate control capabilities
  - "Full-function" capability to control full ring, energy ramp, injection flexibility, operational interface
  - "Production System" - final operational hardware, with necessary upgrades and modifications learned from running "Full-Function"

# Research and Technology Timeline



- Essential goal - be ready at end of LS2 with full-function system ready to commission
- SPS upgrade after LS2 ( new injector, higher currents, new operational modes)
- We must use the demo system, MD time post LS1 to validate control ideas, validate kicker and technical approach. Full Function is only 1 design iteration away from Demo System.

# FY2013/2014 Development path - Research Areas

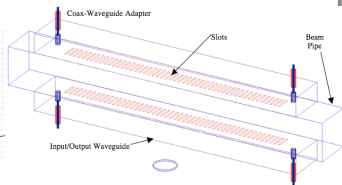
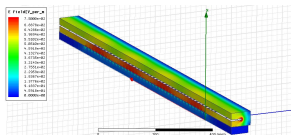
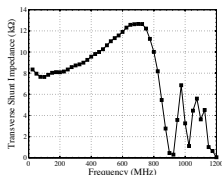
- During LS1 shutdown interval
- Expand Demo system ( M&S costs in FY2012 \$)
  - Low-noise transverse coordinate receivers, orbit offset and pickup techniques (\$25K)
  - Wideband Kicker Prototype for SPS Installation LS1 ( CERN supported LNF fabrication)
  - Expand Master Oscillator, Timing system to synchronize to the SPS RF system, Energy ramp control (\$25K )
  - Expand firmware, design multi-bunch control, explore orbit offset/dynamic range improvements
- Diagnostic and beam instrumentation techniques to optimize feedback parameters and understand system effectiveness
- Continued simulation and modelling effort, compare MD results with simulations, explore new controllers

# Ecloud/TMCI Wideband Feedback "Full-Function Deliverable"

- Full-Function deliverable completed in FY18 for commissioning in FY19
  - "Full-Function" - capability to control full ring at high intensity
  - "Full-Function" - synchronization during energy ramping
  - Integration of system control/beam diagnostics for operation
- System capability to control full SPS ring at HL upgraded intensity
  - Beam line pickups/kickers
  - Beam motion receiver, processing electronics
  - 4 - 8 Gs/sec DSP for intra-bunch feedback
  - System Timing, Synchronization Clocks/Oscillators
  - GHz bandwidth Kicker(s), Power Amplifiers
  - Operator interfaces, control/monitoring software
  - Beam diagnostic software, configuration software
  - Accelerator Dynamics models, Stability tools
- Areas of SLAC/CERN contributions
  - SLAC - Feedback signal processing and control software, diagnostic software
  - CERN - tunnel based vacuum Components ( kickers) and cable plant
  - Opportunity for collaborative engineering team, shared operational expertise

# Kicker Options Design Study ( J. Cesaratto)

- LNF-INFN,LBL and SLAC Collaboration. Excellent progress 2012-2013
- Goals - evaluate 3 possible options. Design Report June 2013
- Based on requirements from feedback simulations, shunt impedance, overall complexity - Provide CERN with a recommendation of which kicker technologies to fabricate.



# CERN Contributions and SPS Plans

- Material from Wolfgang Hofle

# Full-Function Wideband Feedback LARP Deliverables

- FY15 - FY16 Design studies Full-Function System
  - Simulation of full-function control algorithm, multi-bunch and multi-stack
  - System specification, capability specification, in conjunction with Demo System MD measurements
- FY17 - FY 18 Full-Function System design and fabrication
  - "Full-Function" capability for all bunches in SPS, energy ramp, operational flexibility ( e.g. 10 ns scrubbing fill, flexible SPS cycles)
  - Operational interface, control path to CERN CCR
  - "Full-Function" implementation anticipates operational needs and capabilities as indicated from tests with 1 bunch Demo system
- FY19 - reduced manpower to commission/test system at SPS after LS2
- SLAC's contribution - all low-level signal processing, DSP functions, synchronization functions, operational interface
- CERN's contribution - All vacuum structures ( pickup, low and high band kickers) all tunnel cable plant
- Potential shared contributions - High Power kicker amplifiers ( low band, high band)



# FY2015/2016 Research plans, Technology development path, M&S plans ( M&S costs FY2012 \$)

- MD measurements with wideband DEMO system (SPS beam time and analysis)
  - Diagnostic and beam instrumentation techniques to optimize feedback parameters and understand system effectiveness
  - Continued simulation and modelling effort, compare MD results with simulations, explore new controllers
  - Evaluate options for Kickers ( wideband? dual band?) and upgrade tunnel High-Power wideband RF amplifiers for SPS operation (\$50K)
- Technology Development and system estimation for Full-function system
  - Wideband 20 - 1000 MHz RF power amplifiers, with acceptable phase response (\$75K)
  - RF Support for SPS tests ( \$25K)
- High-speed DSP Platform consistent with 4 -8 GS/sec sampling rates for full SPS implementation (\$75K )
  - lab evaluation and firmware development
  - estimation of possible bandwidths, technology options for deliverable

# FY2017/2018 Technology development path, M&S Plans ( M&S costs FY2012 \$)

- FY2017 Continued Demo System Dynamics R&D
- FY2017/2018 Development of Full-function system deliverable ( LS2 2018)
  - Beam Motion receiver ( \$50K)
  - Dynamic range preservation ( orbit offset) processor (\$30K)
  - Front-end delay, timing and synchronization methods (\$20K)
  - SPS Timing System operational interface (\$20K)
  - FPGA Main processing logic motherboard (\$100K)
  - Front End A/D System ( 4-8 GS/s) (\$20K)
  - Back End D/A System ( 4-8 GS/s rate) (\$20K)
  - Back End low level distribution, band split, fanout and timing ( \$40K)
  - Back End Power Amplifiers ( total \$200K)
  - High-Power couplers, monitoring and diagnostic mux systems (\$40K)
  - User interface processor and firmware for operations (\$35K)
  - Lab hardware, engineering model components (future critical spares) (\$75K)

# FY2019 Research and Commissioning Plans

- Post LS2 Commission SPS Full-function Wideband Feedback system deliverable
  - MD measurements, analysis
  - Publication of research results ( Grad student thesis)
  - Adaptation of Demo system for PS test/use
  - Specification of LHC system, LHC system proposal
- Commissioning effort is joint SLAC/CERN activity, allows CERN to develop operational expertise, investment in implementation technology
- (Possible transfer of Demo system to PS for development and MD studies)

# Manpower and Skills Overview

## • Necessary Skills and Capabilities

- Accelerator modelling and dynamics
- MD measurements and data analysis
- Control theory and techniques
- Wideband RF ( pickups, kickers, beam motion receivers)
- GS/s Digital signal processing
- Project management and planning

## • Manpower

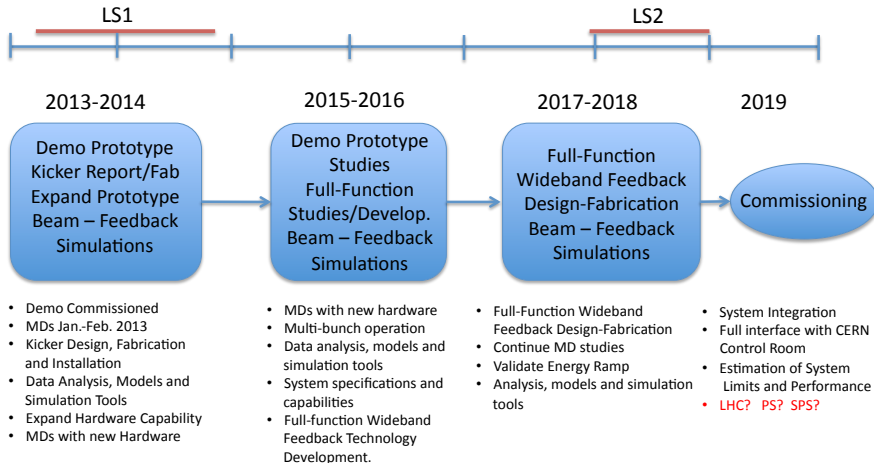
- SLAC based - signal processing contributions
  - Staff Physicists and Engineers
  - Toohig Fellow and/or Postdoctoral Research Associate
  - Graduate Students
- CERN based
  - MD coordination
  - Potential firmware contribution
- Kicker Structures and Tunnel cable plant
  - CERN funded, CERN managed
  - Design report with SLAC/LBL/LNF authors
  - LNF to fabricate prototype under LIU HL program

# Manpower - Research vs. Deliverable System Development

- Rationale by skill set, numbers and year 13-14, 15-16,17-18
- Balance between research/education component ( grad students, Fellow) vs. Simulation/dynamics effort , Engineering skills required
- Possible coordination with CERN Engineering and Accelerator Physics skills
  - DSP firmware ( SLAC and CERN)
  - Pickup and Kicker implementation ( CERN and LNF)
  - Front end, Receiver ( SLAC)
  - Master Oscillator, Timing system (SLAC and CERN)
  - Back end, Power stages ( SLAC and CERN)
  - Diagnostic and beam motion analysis techniques ( SLAC, CERN and LNF)
  - Nonlinear Beam and Feedback Simulations ( CERN and SLAC)

		FULL FUNCTION DELIVERABLE - HIGH BANDWIDTH INTRA-BUNCH INSTABILITY FEEDBACK SYSTEMS Full function deliverable available for test after L32													
		Revision #13.1 Cesaratto, J. Fox, C. Rivetta, based on 1 full function deliverable and "supplied" SLAC labor rates													
		Revision Date: 06/06/2012													
		Brief Scope Description and Assumptions													
		S1		S2		S3		S4		S5		Total w/o Contingency		Contingency %	Total incl. Contingency
		FY12 BASE	FY13	FY14	FY15	FY16	FY17	FY18	FY19	FY20	FY21	FY22			
M&S Location		2,700%	5,47%	8,12%	11,24%	14,24%	17,32%	20,49%	23,74%	27,08%	30,51%	34,03%			
Labor Location		0,80%	2,82%	5,30%	8,02%	10,72%	13,40%	16,33%	19,44%	22,74%	26,23%				
DEVELOPMENT/EXPANSION OF DEMONSTRATION PROCESSING SYSTEM															
M&S		\$100,000	\$0	\$62,730	\$64,340								\$106,890		\$341,630
Synchronization function for energy ramp		\$25,000	\$0	\$16,168	\$16,588								\$26,168	33%	\$35,370
Receiver channel development, prototype		\$25,000	\$0	\$16,168	\$16,588								\$26,168	33%	\$35,370
High bandwidth receiver power system, prototype		\$50,000	\$0	\$30,336	\$31,164								\$52,352	33%	\$70,930
Labor		\$975,000	\$982,800	\$1,002,495									\$1,985,295		\$1,285,295
Staff Scientist, 2 FTE		\$600,000	\$602,400	\$616,500									\$1,221,720	0%	\$1,221,720
Staff Engineer, 1 FTE		\$180,000	\$182,400	\$187,500									\$375,000	0%	\$375,000
Fellow/Postdoc, 1 FTE		\$180,000	\$181,400	\$185,070									\$366,510	0%	\$366,510
Graduate Student, 2 FTE (50% cost split with SLAC)		\$95,000	\$95,760	\$97,679									\$193,430	0%	\$193,430
DESIGN STUDIES OF FULL-FUNCTION PROTOTYPE, SIMULATIONS, MDs with 1 bunch Demo															
M&S		\$175,000		\$106,120	\$83,430								\$191,750		\$254,000
Travel expenses for staff and evaluations		\$191,750		\$121,545	\$97,545								\$219,405	33%	\$290,760
High capacity processing channel (logic processing functions)		\$25,000	\$0	\$16,168	\$16,588								\$26,168	33%	\$35,370
High capacity processing channel, 2nd FPGA platform for development		\$25,000	\$0	\$16,168	\$16,588								\$26,168	33%	\$35,370
Labor		\$1,130,000		\$1,180,140	\$1,209,824								\$2,390,192		\$2,868,330
Staff Scientist, 2.25 FTE		\$675,000		\$711,188	\$729,135								\$1,440,518	20%	\$1,728,023
Staff Engineer, 1.25 FTE		\$190,000		\$198,800	\$203,700								\$396,900	20%	\$476,280
Fellow/Postdoc, 1.25 FTE		\$270,000		\$284,550	\$293,054								\$576,207	20%	\$691,448
Graduate Student, 2 FTE		\$95,000		\$100,121	\$103,619								\$202,740	20%	\$243,288
DESIGN AND FABRICATION OF A FULL-FUNCTION DELIVERABLE WITH CONTROL INTERFACE															
M&S (cost per system, based on one system)		\$715,000				\$591,272	\$519,341						\$991,613		\$1,365,820
Front end hybrid and beam motion receiver		\$500,000				\$417,120	\$367,120						\$724,240	50%	\$1,090,000
Dist-off and dynamic range preservation processor		\$300,000				\$244,272	\$215,000						\$359,272	50%	\$533,400
Front end variable delay and timing alignment		\$200,000				\$162,864	\$143,464						\$246,364	50%	\$369,100
Timing and synchronization system for interface to accelerator		\$200,000				\$162,864	\$143,464						\$246,364	50%	\$369,100
PGA signal processing channel (logic processing functions)		\$100,000				\$81,424	\$71,732						\$123,156	50%	\$184,660
Front end A/D system for 4 GS/s rate		\$100,000				\$81,424	\$71,732						\$123,156	50%	\$184,660
Back end D/A system for 4 GS/s operation		\$100,000				\$81,424	\$71,732						\$123,156	50%	\$184,660
Back end beam distribution, beam pickup, feedback and timing distribution channels		\$100,000				\$81,424	\$71,732						\$123,156	50%	\$184,660
Self-supply power system, 1.4MW, 400V, 50Hz, 1000A, 1000V, 500A, 1															

# Project Timeline



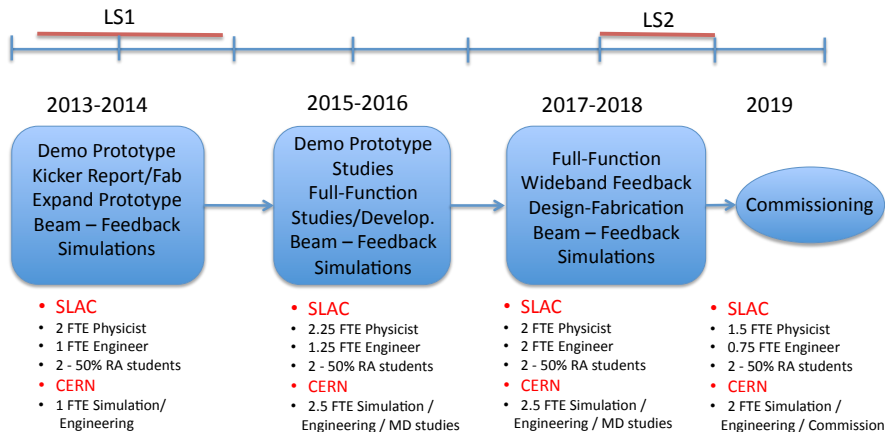
- Essential goal - be ready at end of LS2 with full-function system ready to commission
- SPS upgrade after LS2 ( new injector, higher currents, new operational modes)
- We must use the demo system, MD time post LS1 to validate control ideas, validate kicker and technical approach. Full Function is only 1 design iteration away from Demo System.

# Labor Cost Methodology

- Labor costs based on SLAC overhead and numbers from representative typical rates
- Mix of Student/fellow contributions, Lab Staff ( physicist/engineer) contributions
- 50% grad student support, 50% assumed support from SLAC ARD GARD funds
- Would benefit from availability of Toohig Fellow ( but as extra manpower)
- Does not include any LBL, LNF or CERN manpower as a LARP cost
- Costs include escalation and contingency per DOE model

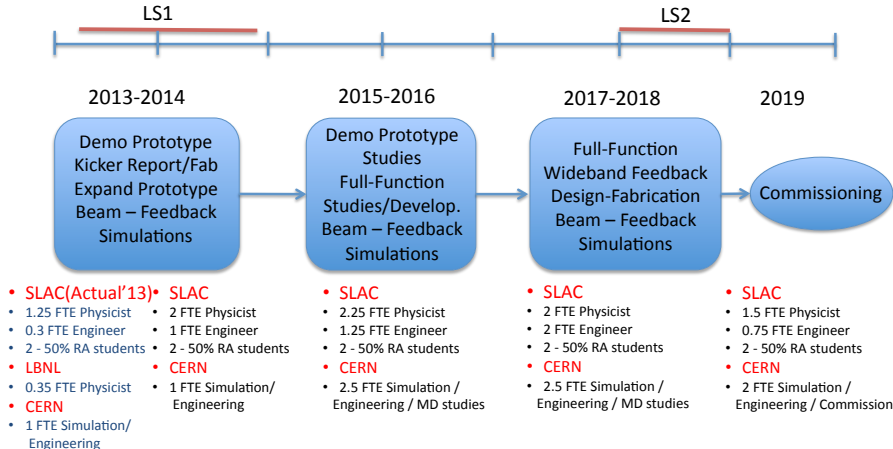


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# Technology and System Development Cost Methodology

- Catalog prices for purchased items ( eg power amplifiers, delay lines)
- Consistency with project technology development costs to date ( fab of Demo and Excite systems)
- System capabilities estimated based on best knowledge from simulations, MD results and experience
- Plan for deliverable system, engineering model will become spare for operations
- Costs include escalation and contingency per DOE model

## Other costs carried in budget

- Travel for MD measurements, conferences, accelerator schools
- Lab equipment ( e.g. test/measurement necessary for design/evaluation, prototype hardware evaluations, MD instrumentation, software for E&M design and FPGA design) - TBD amounts, partial split with GARD funds

# Risks and Mitigation

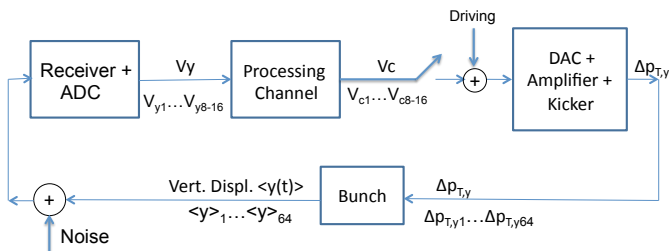
- Successful 1 bunch Demo and initial MD effort is excellent start to show ability to meet schedule requirements and technical competence
- Technical Risks - Uncertainty in required bandwidth, control methods for non-linear system, complexity/type of control algorithm, necessary system power, etc.
  - Mitigations in reconfigurable FPGA algorithm, scalable power stages, possibility of adding extra kickers or multiple kicker technologies.
  - Confidence from post LS-1 multi-bunch tests, decision point before fab of full-function deliverable
- Demonstrated risk - underfunding of necessary FY13-14 effort
  - example, FY13 budget plan, underfunding of actual FY13 year
  - limitation of engineering contribution to 12.5% FTE
  - Guarantees project is late starting in FY14, loses important time this year to work on critical system capabilities ( energy ramp, multi-bunch capability, etc.) necessary for post LS1 MD program.
  - FY14 amplifier evaluation pushed back into FY15 due to budget limits
  - Lack of manpower assignment authority means risk of loss of critical signal processing engineer, loss of continuity of project progress

# Summary and Discussions

- "Full Function " as deliverable - original plan was to make PS, SPS and LHC production systems after full-function
- roughly 30% extra cost to make actual production systems based on operational experience from Full-function prototype
  - manpower is extremely lean for combined research and engineering effort
  - research aspect, Ph.D. students and new control ideas are inexpensive but not luxuries to be cut out to save \$
  - System design is reconfigurable, allowing future improvements
  - Operational software, operator integration within CERN environment is potentially beyond scope of this deliverable
  - CERN interest in multiple systems for the PS , SPS and LHC
  - CERN interest in development of accelerator diagnostics as function within feedback channel
- Discussions with Reviewers
  - Project funding is 80% salaries, overheads - technical component is 13 - 20%
  - Realistic plans for FY 13, 14 - necessary timing and synchronization functions
  - importance of original FY13 and FY14 planning, including amplifier evaluations
  - Critical and vital installation of wideband kicker into SPS at end of LS1
  - Importance of MD program in FY15, modelling effort to verify control algorithms and system features

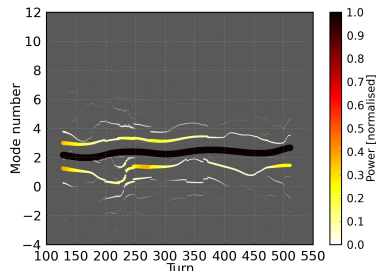
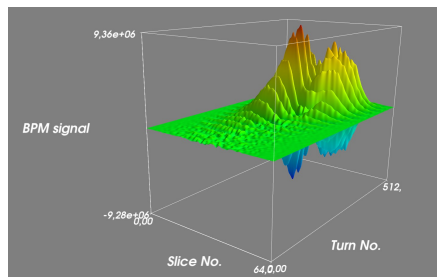
# Progress in Simulation Models

- Critical to **validate simulations against MD data**
- Still needs realistic channel noise study, sets power amp requirements
- Still needs more quantitative study of kicker bandwidth requirements
- Head-tail offers path to evaluate TMCI and feedback methods
- Continued progress on linear system estimation methods
- Model test bed for **controller development**



# HeadTail study - Ecloud driven instability of SPS

Ecloud instability,  $10^{11}$  protons/bunch,  $\rho_e \approx 6 \times 10^{11} e^- m^{-3}$

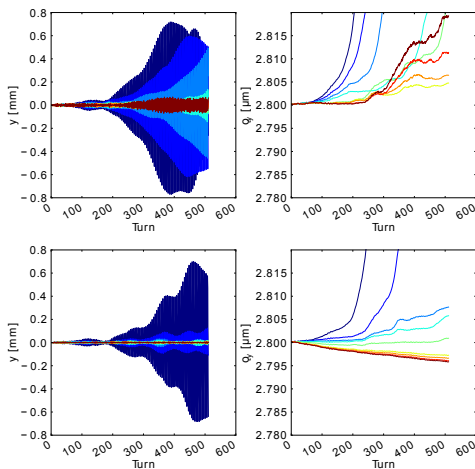


- Clear coherent motion above the instability threshold
- The mode evolution reveals the presence of predominantly modes  $\{0, -1, -2\}$  (shifted)



# Macro-Particle Simulation Codes- HeadTail

- Electron cloud interaction with a bunch of  $1.1 \times 10^{11}$  protons.



Kicker  $BW = 200$  MHz.

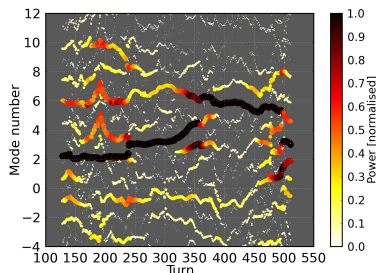
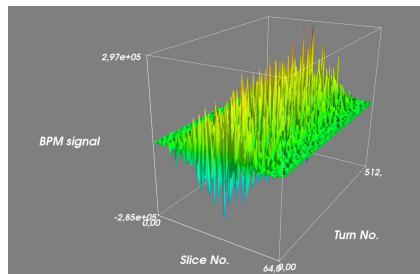
- Motion is unstable at all gain settings

Kicker  $BW = 500$  MHz.

- Evolution of the bunch centroid motion and the normalized emittance for different gains  $G$ .
- Motion is stable for gain  $>$  threshold
- Ecloud density  $= 6 \times 10^{11} e/m^3$

# HeadTail study - simplified feedback, 500 MHz Kicker

Ecloud instability,  $10^{11}$  protons/bunch,  $\rho_e \approx 6 \times 10^{11} e^- m^{-3}$



- Clear damping of the coherent motion
- Remaining power is distributed over modes  $\{2,6\}$
- Nonlinear system, difficult to quantify margins

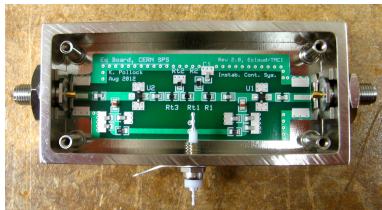
# Technology Development for SPS tests



- Timing and synchronization master oscillator
- Beam Motion Receiver (delta/sigma system)
- 4(3.2) GS/sec. Beam excitation system (arbitrary waveform generator, 15K turns)
- 4(3.2) GS/sec. DSP Feedback Demo processor
- Tunnel amplifiers/control for beam excitation ( $4 \times 80\text{W}$  1 GHz)

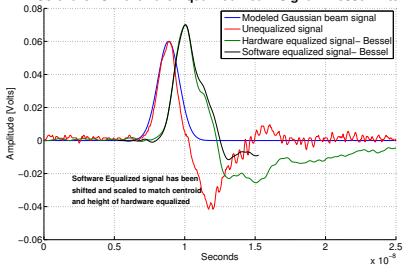
**The goal is to build general purpose testbed components to allow machine measurements, experiments of fundamental control ideas using the SPS**

# Hardware Equalizer



- Pickup response distorts beam signals
- Long cables also have nonlinear phase response
- Existing software equalizer used in matlab data processing
- we need a real-time ( hardware) equalizer for processing channel
- Optimization technique - can be used for kicker. too

Software vs. Hardware Equalized Beam Signal- Bessel Filter



# Feedback algorithm complexity and numeric scale

Frequency spectrograms suggest:

sampling rate of 2 - 4 GS/sec. (Nyquist limited sampling of the most unstable modes)

Scale of the numeric complexity in the DSP processing filter

- measured in Multiply/Accumulate operations (MACs)/sec.

**SPS** -5 GigaMacs/sec (  $6 \times 72 \times 16 \times 16 \times 43 \text{ kHz}$  )

- 16 samples/bunch per turn, 72 bunches/stack, 6 stacks/turn, 43 kHz revolution frequency
- 16 tap filter (each slice)

**KEKB** (existing iGp system) - 8 GigaMacs/sec.

- 1 sample/bunch per turn, 5120 bunches, 16 tap filters, 99 kHz revolution frequency .

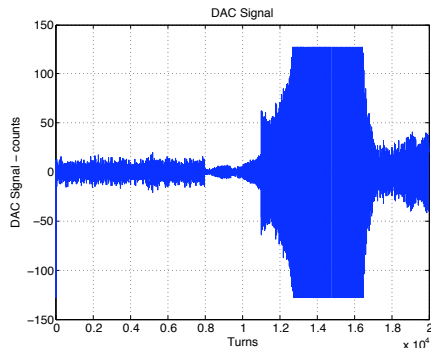
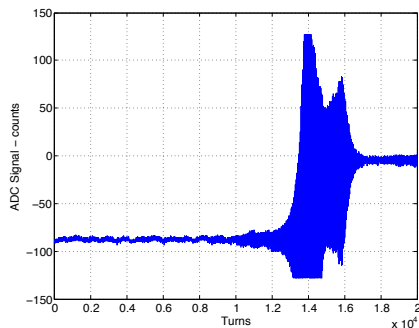
The **scale** of an FIR based control filter using the single-slice diagonal controller model is **not very different** than that achieved to date with the coupled-bunch systems.

What is **different** is the **required sampling rate** and **bandwidths** of the pickup, kicker structures, plus the need to have **very high instantaneous data rates**, though the average data rates may be comparable.

# MD Feedback studies on unstable or marginally stable beams

- Manipulate feedback parameters, study free beam responses
- Feedback control as time-varying parameter (on, off, variable gains, filters, Positive/Negative feedback etc.)
- Study changes in dynamics vs. feedback configuration (grow/damp studies)
- Manipulation of feedback filters allows growth of instability from stable controlled state, measurement in small-amplitude conditions
- Easily measures fastest modal growth rates - requires care to measure slow modes in presence of fast modes
- Disadvantage - requires feedback control to do most studies

# Unstable beam -Input, Output signals via snapshot



- Example of gain reduction during stable control, loss of control after gain restoration 3k turns later. Transient deserves more complete analysis.
- Mode zero unstable beam
- Gain modulated  $\times 8 \times 2 \times 8$  during cycle
- For turns 0-8k, 8k-11k, 11k-end
- Input (left), DSP output (right) Note gain of filter, DC suppression and saturation

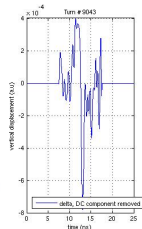
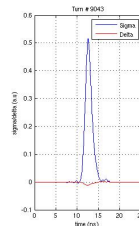
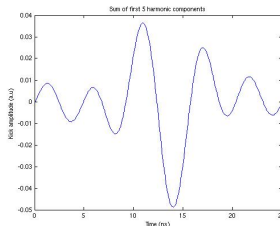
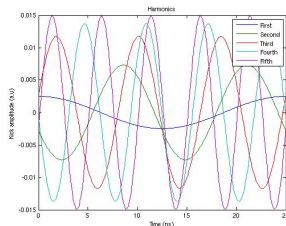
## Future Directions - beam studies

- The Demo platform is a reconfigurable testbed for control techniques
- Provides unique beam diagnostics and opportunities for new measurement methods
- Studies of unstable systems are difficult, control and time varying gain is a useful method (grow-damp techniques)
- To date, unstable beams available have had mode zero instabilities, we want to study higher internal modes
- Complementary methods with driven responses
- We are eager to collaborate on novel beam diagnostics and measurement techniques, analysis methods
- Analysis of recent MD transients will require some time, future talks and discussions



# Implications from the 25ns bunch spacing

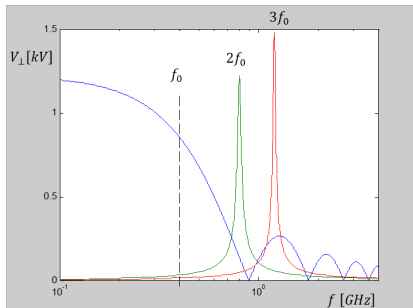
- Sandro's note, Dmitry's contributions - Basic themes
  - Correction signal is wideband in time scale of 2 ns bunch ( head-tail, higher excitations)
  - 25 ns bunch interval - allows narrower bandwidth kickers, use 25 ns to get to full scale amplitude
  - Decompose kick into several fundamental "modes" - beam samples and integrates final kick
- Requires multiple output signals, calculation of "modes" vs. parallel scheme, requires multiple operational phasing and equalization requirements



# Kicker Options - Idea from S. Gallo

- Use 25 ns interval between bunches, have kicker with 20 ns fill time
- High shunt impedance, requires more complex off-diagonal processing, input and output data at different rates

	Kicker #1	Kicker #2	Kicker #3
Type	Stripline	Cavity, TM110 defl. mode	Cavity, TM110 defl. mode
3-dB bandwidth	DC – 400 MHz	$800 \pm 16$ MHz	$1200 \pm 16$ MHz
Length	17 cm	15 cm	10 cm
Filling time	0.6 ns	10 ns	10 ns
$Q_L$	---	25	38
Shunt Impedance	$\approx 1.5$ k $\Omega$ (@ DC)	$\approx 1.5$ k $\Omega$ (@ 800 MHz)	$\approx 2.2$ k $\Omega$ (@ 1200 MHz)



Assuming that each kicker is powered by a 1 kW source covering the entire device bandwidth, the resulting transverse voltage transferred to the beam as a function of the frequency is shown in the following plot.